

Generalizing the Single-Crossing Property on Lines and Trees to Intermediate Preferences on Median Graphs

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Abstract

Demange (2012) generalized the classical single-crossing property to the intermediate property on median graphs and proved that the representative voter theorem still holds for this more general framework. We complement her result with proving that the linear orders of any profile which is intermediate on a median graph form a Condorcet domain. We prove that for any median graph there exists a profile that is intermediate with respect to that graph and that one may need at least as many alternatives as vertices to construct such a profile. We provide a polynomial-time algorithm to recognize whether or not a given profile is intermediate with respect to some median graph. Finally, we show that finding winners for the Chamberlin-Courant rule is polynomial-time solvable for profiles that are single-crossing on a tree.

1 Introduction

Condorcet’s famous paradox demonstrates that pairwise majority voting may produce intransitive collective preferences. The question of whether, and if so, how, this problem can be overcome by means of restrictions on the domain of admissible individual preferences has attracted constant interest over the recent decades, see [Gaertner, 2001] for a detailed overview. Probably the best-known domain restriction is single-peakedness [Black, 1948] which is frequently employed in models of political economy. It stipulates that all alternatives can be arranged along one dimension, for instance according to the political left-right spectrum, so that each voter has an ideal choice in the set of alternatives and the alternatives that are further from their ideal choice are preferred less. The concept of single-peakedness itself can be generalized considerably, however, the sufficiency of single-peakedness for transitivity of the (strict) majority relation is confined to the classical one-dimensional case only.¹

A different and frequently useful sufficient condition for transitivity of the majority relation is the single-crossing

property [Mirrlees, 1971]. A profile of individual preferences is said to have the single-crossing property if the voters can be arranged on a one-dimensional linear spectrum so that, for all pairs of alternatives (a, b) , the set of voters who prefer a to b and also the set of voters who prefer b to a are both convex. As shown by Rothstein [1991], every single-crossing profile has a so-called *representative voter*, i.e., a voter whose (strict) preference coincides with the (strict) majority relation.²

Roberts [1977], Blair and Crawford [1984], Gans Smart [1996] provide a number of economic applications of single-crossingness among which are voting models of redistributive income taxation and trade union bargaining. All of them represent situations when preferences of individuals depend on a single parameter while in practice we may have a number of them. So there are compelling economic reasons which prompt us to consider single-crossingness on graphs more general than a line. Kung [2014], in particular, argues that single-crossingness on trees can be applied to the study of networks.

In contrast to the case of single-peaked preferences, the sufficiency of the single-crossing property for transitivity of the strict majority relation generalizes to median graphs [Demange, 2012], which, in particular, include trees and lattice graphs. This generalisation is based on the notion of intermediate preferences [Grandmont, 1978]. Assume that voters can be indexed by the vertices of a graph, and say that a profile satisfies the *intermediateness property* (or simply that it is *intermediate*) with respect to this graph if, for all pairs of alternatives (a, b) and any two voters i and j who prefer a to b , all voters that lie on any shortest path between i and j on the graph also prefer a to b . Evidently, if the graph is a line, a profile satisfies the intermediateness property if and only if it satisfies the single-crossing property.

The purpose of this paper is two-fold. Firstly, we prove that any profile which is intermediate on a median graph gives rise to a Condorcet domain. We give a constructive proof of the existence of an intermediate profile for any median graph with n vertices (generalising and strengthening the corresponding result of Kung for trees). We prove that n alternatives are always sufficient and that there exists a median graph (actually a tree) for which intermediate profiles

¹Single-peakedness on trees still guarantees the existence of a Condorcet winner, and single-peakedness on a median graph the existence of a “local” Condorcet winner [Bandelt and Barthélemy, 1984].

²One can show that such a result does not hold for single-peaked preferences even on a line.

with fewer than n alternatives do not exist. We also give a polynomial-time algorithm that recognizes whether or not a given profile is intermediate with respect to some median graph. Finally, we prove that the Chamberlin-Courant multi-winner voting rule on single-crossing profiles on trees has a polynomial time winner-determination problem which generalises a similar result of Skowron et al. [2013] for the classical single-crossing property. The corresponding problem on median graphs remains open. It is interesting to note that for the single-peaked property on a tree only the egalitarian version of the Chamberlin-Courant rule remains polynomial. The classical utilitarian version of this rule becomes NP-hard [Yu et al., 2013].

The problem addressed in the present paper is closely related to the search of maximal Condorcet domains [Abello and Johnson, 1984; Abello, 1991; Galambos and Reiner, 2008; Danilov et al., 2012]; see also the survey on the topic in [Monjardet, 2009]. Indeed, any intermediate profile on a median graph provides us with a new type of Condorcet domain (although possibly not maximal).

2 Preliminaries

2.1 Linear orders and profiles

Let A and V be two finite sets of cardinality m and n , respectively. The elements of A will be called alternatives, the elements of $V = \{1, 2, \dots, n\}$ voters. We assume that the voters have preferences over the set of alternatives. By $\mathcal{L}(A)$ we denote the set of all (strict) linear orders on A ; they represent the preferences of agents over A . The elements of the Cartesian product $\mathcal{L}(A)^n = \mathcal{L}(A) \times \dots \times \mathcal{L}(A)$ (n times) are called n -profiles or simply profiles. They represent the collection of preferences of the voters from V over the alternatives from A . If a linear order R_i represents the preferences of the i -th voter, then by $aR_i b$, where $a, b \in A$, we denote that this agent prefers a to b . We also denote this as $a \succ_i b$.

Given a profile $R = (R_1, \dots, R_n)$, we say that a linear order R_j is between orders R_i and R_k if $a \succ_i b$ and $a \succ_k b$ imply $a \succ_j b$ for every pair of alternatives $a, b \in A$. The set of all linear orders from R that are between R_i and R_k is denoted $[R_i, R_k]$.

Definition 2.1. Let $R = (R_1, \dots, R_n)$ be a profile. The majority relation $M(R)$ of R over A is the binary relation on A such that for any $a, b \in A$ we have $a \succeq b$ if and only if $|\{i \mid a \succ_i b\}| \geq |\{i \mid b \succ_i a\}|$.

We will also write $a \succ b$ if $a \succeq b$ but not $b \succeq a$ and call it the *strict majority relation*. When n is odd, the majority relation coincides with the strict majority relation and is a tournament on A , i.e., a complete and asymmetric binary relation.

Definition 2.2. A Condorcet domain is a set of linear orders $C \subseteq \mathcal{L}(A)$ such that, no matter how many voters in the profile P have each of the linear orders from C as their preference relation, the strict majority relation of P is transitive.

Condorcet domains have long been of interest to Social Choice scientists and mathematicians alike; see the aforementioned survey by Monjardet. For a detailed discussion of single-crossing condition see [Bredereck et al., 2013].

2.2 Median Graphs, Geodesic Convexity and Geodesic Betweenness

Let $G = (V, E)$ be a connected graph. The *distance* $d(u, v)$ between two vertices $u, v \in V$ will be the smallest number of edges that a path from u to v may contain. While the distance is uniquely defined, there may be several shortest paths from u to v . We say that vertex w is *geodesically between* vertices u and v if w lies on a shortest path that connects u and v or, alternatively, $d(u, v) = d(u, w) + d(w, v)$.

Definition 2.3. A (geodesically) convex set in a graph $G = (V, E)$ is a subset $C \subseteq V$ such that for any two vertices $u, v \in C$ all vertices of any shortest path between u and v in G lie entirely in C .

Definition 2.4. A connected graph $G = (V, E)$ is called a median graph if for any three distinct vertices $u, v, w \in V$ there is a unique vertex $m(u, v, w)$, called median, which lies on shortest paths from u to v , from u to w and from v to w .

Trees and lattice graphs are examples of median graphs. It is known that median graphs are bipartite and hence do not contain triangles [Bandelt and Barthélemy, 1984].

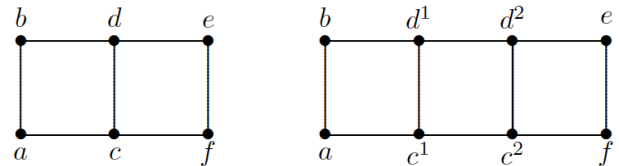
To describe the structure of an arbitrary median graph we remind the concept of *convex expansion* for graphs.

Definition 2.5. Let $G = (V, E)$ be a graph. Let $W_1, W_2 \subset V$ be subsets such that $W_1 \cup W_2 = V$, $W_1 \cap W_2 \neq \emptyset$ and there are no edges connecting vertices of $W_1 \setminus W_2$ and vertices of $W_2 \setminus W_1$. The expansion of G with respect to W_1 and W_2 is the graph G' constructed as follows:

- each vertex $v \in W_1 \cap W_2$ is replaced by two vertices v^1, v^2 joined by an edge;
- v^1 is joined to the neighbours of v in $W_1 \setminus W_2$ and v^2 is joined to the neighbours of v in $W_2 \setminus W_1$;
- if $v, w \in W_1 \cap W_2$ and $vw \in E$, then v^1 is joined to w^1 and v^2 is joined to w^2 .

If W_1 and W_2 are convex, then G' will be called a convex expansion of G .

Example 2.6 (Convex expansion). In the graph G shown on the left of the following figure we set $W_1 = \{a, b, c, d\}$ and $W_2 = \{c, d, e, f\}$. These are convex and their intersection $W_1 \cap W_2 = \{c, d\}$ is not empty. Also the vertices of $W_1 \setminus W_2 = \{a, b\}$ and $W_2 \setminus W_1 = \{e, f\}$ have no edges between them. On the right we see the graph G' obtained by the convex expansion of G with respect to W_1 and W_2 .



The following important theorem about median graphs is due to Mulder [1978].

Theorem 2.7 (Mulder's convex expansion theorem). A graph is a median graph if it can be obtained from a trivial one-vertex graph by repeated convex expansions.

3 Intermediateness property

Let $G = (V, E)$ be a graph with $V = \{1, \dots, n\}$ and $R = (R_1, \dots, R_n)$ be a profile. We will consider the linear orders of R as indexed by vertices of G .

Theorem 3.1. *Let $G = (V, E)$ be a graph with $V = \{1, \dots, n\}$ and $R = (R_1, \dots, R_n) \in \mathcal{L}(A)^n$ be a profile. The following conditions are equivalent:*

- (i) R_j is between R_i and R_k whenever j is geodesically between i and k ;
- (ii) for every ordered pair of alternatives $(a, b) \in A^2$ the set $V_{ab} = \{i \in V \mid a \succ_i b\}$ is convex in G ;
- (iii) for every shortest path i_1, \dots, i_k in G between i_1 and i_k the profile $(R_{i_1}, \dots, R_{i_k})$ is classical single-crossing profile relative to the order of voters determined by that path.

Proof. (i) \Rightarrow (ii). Let $i, k \in V_{ab}$. Consider j on any shortest path from i to k . Then by (i) R_j is between R_i and R_k and since i and k agree on the pair a, b we have $a \succ_j b$, whence $j \in V_{ab}$.

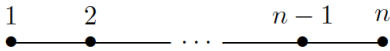
(ii) \Rightarrow (iii). Let $I = \{i_1, \dots, i_k\}$. As I is a shortest path and V_{ab} is convex, then $V_{ab} \cap I$ is a subpath. But $V_{ba} \cap I$ is also a subpath and this can happen only when there exists ℓ such that $V_{ab} = \{i_1, \dots, i_\ell\}$ and $V_{ba} = \{i_{\ell+1}, \dots, i_k\}$.

(iii) \Rightarrow (i). Follows from properties of classical single-crossing profiles. \square

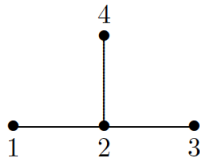
Definition 3.2. *The profile $R = (R_1, \dots, R_n)$ is said to be intermediate on the graph $G = (V, E)$ if one of the equivalent conditions (i) - (iii) of Theorem 3.1 holds.*

Let us consider several examples.

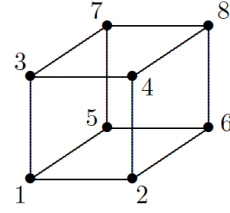
Example 3.3. (a) Classical single-crossingness. *A classical single-crossing profile $R = (R_1, \dots, R_n)$ is intermediate on a path:*



(b) Single-crossing on a tree. *Consider the profile $R = (R_1, R_2, R_3, R_4)$ on the set $\{a, b, c, d\}$ consisting of the following four orders: $R_1 = acbd$, $R_2 = abcd$, $R_3 = abdc$, and $R_4 = bacd$. As is easily seen, this profile is intermediate (single-crossing) on the following tree:*



(c) Intermediate profile on a lattice graph. *The following profile R is made of a set of linear orders which is a maximal Condorcet domain: $R_1 := abcd$, $R_2 := abdc$, $R_3 := bacd$, $R_4 := badc$, $R_5 := cdab$, $R_6 := dcab$, $R_7 := cdba$, $R_8 := dcba$. It can be checked that R is intermediate on the cube:*



Definition 3.4. *Let $P \in \mathcal{L}(A)^n$ be a profile which is intermediate on a median graph $G = (V, E)$ and $a, b \in A$. An edge $uv \in E$ is said to be an ab -cut if $a \succ_u b$ and $b \succ_v a$.*

Unlike for trees an ab -cut may not be unique (although [Demange, 2012] claims that it is). Given an edge e let us denote $S(e) = \{(a, b) \in A^2 \mid e \text{ is an } ab\text{-cut}\}$.

Lemma 3.5. *Let P be a profile which is intermediate on a median graph $G = (V, E)$. An edge $e = uv \in E$ is an ab -cut if and only if $V_{ab} = \{w \in V \mid d(w, u) < d(w, v)\}$, and $V_{ba} = \{w \in V \mid d(w, u) > d(w, v)\}$.*

Proof. Let $w \in V_{ab}$. Then, due to intermediateness, among w, u, v only u can be the median. Hence wuv is the shortest path from w to v and $d(w, u) = d(w, v) - 1$ and $d(w, u) < d(w, v)$. The converse is clear. \square

Corollary 3.6. *Let P be a profile which is intermediate on a median graph $G = (V, E)$. Suppose $e_1, \dots, e_k \in E$ are ab -cuts. Then $S(e_1) = \dots = S(e_k)$.*

Proof. Suppose $e_1 = u_1v_1$ is an ab -cut and also a cd -cut. Then by Lemma 3.5 $V_{ab} = V_{cd}$ and $V_{ba} = V_{dc}$. Since $e_i = u_iv_i$ is an ab -cut, then $u_i \in V_{ab} = V_{cd}$ and $v_i \in V_{ba} = V_{dc}$. Hence e_i is also a cd -cut. \square

We need the following technical lemma now.

Lemma 3.7. *Let $P = (P_1^{k_1}, \dots, P_n^{k_n})$ be a profile, where linear order P_i is repeated k_i times and $P_i \neq P_j$ if $i \neq j$. If P is intermediate on a median graph G , then the profile $\hat{P} = (P_1, \dots, P_n)$ is also intermediate on a median graph.*

Proof. Any two identical linear orders are either neighbors in G or connected by a path of vertices with identical linear orders. Contracting them to a single vertex results in the graph sought for. \square

Let P be a profile. By $\mathcal{D}(P)$ we denote the set of all distinct linear orders present in P . If all linear orders of P are different, we call the profile P reduced.

Theorem 3.8. *Let P be a profile which is intermediate with respect to a median graph $G = (V, E)$. Then $\mathcal{D}(P)$ is a Condorcet domain.*

Proof. By Lemma 3.7 we may assume that the profile P is reduced. Let $Q = (Q_1^{s_1}, \dots, Q_n^{s_n})$ be a profile with $Q_i \in \mathcal{D}(P)$ and $Q_i \neq Q_j$ for all $i \neq j$. We can add linear orders Q_{m+1}, \dots, Q_n so that the extended profile $\hat{Q} = (Q_1, \dots, Q_n)$ is intermediate on a median graph $G = (\hat{V}, E)$, where $\hat{V} = \{1, \dots, n\}$ (renumeration of vertices may be necessary). We will also denote $V = \{1, \dots, m\}$.

Suppose that $a \succ b$ and $b \succ c$, where \succ is the majority relation for Q . Then we have two partitions of V , namely,

$V = V_{ab} \cup V_{ba}$ and $V = V_{bc} \cup V_{cb}$. We have $|V_{ab}| > |V_{ba}|$ and $|V_{bc}| > |V_{cb}|$. Obviously, $V_{abc} = V_{ab} \cap V_{bc} \neq \emptyset$ since each of these sets contains a majority of voters in V . We have $V_{ab} \subseteq \widehat{V}_{ab}$ and $V_{bc} \subseteq \widehat{V}_{bc}$, where $\widehat{V}_{xy} = \{i \in \widehat{V} \mid x \succ_i y\}$. We cannot claim that \widehat{V}_{ab} or \widehat{V}_{bc} contains more than half of all elements of \widehat{V} but we know that $\widehat{V}_{ab} \cap \widehat{V}_{bc} \supseteq V_{abc} \neq \emptyset$.

Consider now \widehat{V}_{ac} and \widehat{V}_{ca} . Suppose there are several edges $e_s = u_s v_s$ ($s = 1, \dots, t$), connecting them; all of them are ac -cuts. Suppose $\widehat{V}_{ac} \cap \widehat{V}_{ab} \neq \emptyset$ and $\widehat{V}_{ca} \cap \widehat{V}_{ab} \neq \emptyset$. Then for any $p \in \widehat{V}_{ac} \cap \widehat{V}_{ab}$ and $q \in \widehat{V}_{ca} \cap \widehat{V}_{ab}$ the shortest path between them includes one of the ac -cuts, say $e_i = u_i v_i$. This means that $a \succ_{u_i} b$ and $a \succ_{v_i} b$. But then it is not possible to have $\widehat{V}_{ac} \cap \widehat{V}_{bc} \neq \emptyset$ and $\widehat{V}_{ca} \cap \widehat{V}_{bc} \neq \emptyset$ since in this case we would have $b \succ_{u_i} c$ and $b \succ_{v_i} c$ and by transitivity $a \succ_{u_i} c$ and $a \succ_{v_i} c$ which contradicts to e_i being an ac -cut. Since $\emptyset \neq V_{abc} \subseteq \widehat{V}_{ac} \cap \widehat{V}_{bc}$, we have $\widehat{V}_{ca} \cap \widehat{V}_{bc} = \emptyset$ and $V_{bc} \subseteq V_{ac}$. This means $a \succ c$ and \succ is transitive. \square

Now we are going to prove that for any median graph we can construct a reduced profile which is intermediate on that particular graph. We then discuss how many alternatives may be needed.

Theorem 3.9. *For every median graph $G = (V, E)$ with $|V| = n$ there exists a reduced preference profile $R = (R_1, \dots, R_n) \in \mathcal{L}(Y)^n$ on a set of alternatives Y with $|Y| \leq n$ such that R is intermediate on G .*

Proof. Since the statement is true for the trivial graph consisting of a single vertex, arguing by induction, we assume that the statement is true for all median graphs with k vertices or less. Let $G' = (V', E')$ be a median graph with $|V'| = k + 1$. By Mulder's theorem G' is a convex expansion of a certain median graph $G = (V, E)$ relative to convex subsets W_1 and W_2 , where $|V| = \ell \leq k$. By induction there exists a reduced profile $R = (R_1, \dots, R_\ell) \in \mathcal{L}(X)^\ell$ with $|X| \leq k$ which is intermediate on G .

To obtain a new profile R' which is intermediate on G' we clone an arbitrary alternative $x \in X$ and introduce a clone $y \notin X$ of x .³ The linear orders of the new profile R' will be constructed as follows. If v is a vertex of $W_1 \setminus W_2$ to obtain R'_v we replace x with xy in R_v placing y lower than x and to obtain R'_u for $u \in W_2 \setminus W_1$ we replace x with yx in R_u placing y higher than x . Let v now be in $W_1 \cap W_2$. In the convex expansion this vertex is split into v^1 and v^2 . To obtain R'_{v^1} we clone the linear order R_v replacing x with xy and to obtain R'_{v^2} we clone the same linear order R_v replacing x with yx . We have $Y = X \cup \{y\}$ so the number of alternatives has increased by one, so it is not greater than $k + 1 = |V'|$. The profile R' , so obtained, is also reduced.

To prove that R' is intermediate on G' , we need to consider several cases. For example, let $u \in W_1 \setminus W_2$ and $v \in W_2 \setminus W_1$ and let us prove that all linear orders on a shortest path between u and v are between R'_u and R'_v . Firstly, we note that any such shortest path will contain an edge $e = w^1 w^2$, where $w \in W_1 \cap W_2$. There is the corresponding path in G ,

³We say that x and y are clones if they are neighbours in any linear order of the domain (cf. Elkind et al (2011) and (2012)).

where the edge e is contracted to w and all linear orders on that path are between R_u and R_v . The way we placed y in these linear orders will not disturb the betweenness since all linear orders R'_z between R'_u and R_{w^1} (inclusive) will have $x \succ'_z y$ and all others will have $y \succ'_z x$. All other cases are considered similarly. \square

The constant n in this theorem cannot be improved even for trees. However we must exclude some trivial cases. For example, if all the linear orders in a profile are equal, then it is intermediate for any graph. So we have to restrict ourselves to reduced profiles.

Theorem 3.10. *For the star S_n with n vertices (the complete bipartite graph $K_{1, n-1}$) there does not exist a reduced profile $R = (R_1, \dots, R_n) \in \mathcal{L}(X)^n$ on the set X of alternatives of cardinality smaller than n which is intermediate on S_n .*

Proof. We reason by induction on n . The base case is the star S_2 with two vertices for which the result is clear.

Let us assume that for S_n , $n \geq 2$, we cannot construct a reduced profile with less than n alternatives which is intermediate on S_n . Consider S_{n+1} and suppose towards a contradiction that we can find a reduced profile $P = (P_1, \dots, P_{n+1})$ with n alternatives which is intermediate on S_{n+1} . Suppose that the vertices of S_{n+1} are numbered so that voter 1's vertex has degree n and voter 1 has preferences expressed by the linear order $a_1 \succ_1 a_2 \succ_1 \dots \succ_1 a_n$. Suppose, first, that s is the smallest number for which one of the edges, say the one connecting 1 with $n+1$, is an $a_1 a_s$ -cut for S_{n+1} ; if such a number does not exist, a_1 can be removed from the profile and it will stay reduced. Then $a_s \succ_{n+1} a_1$ and $a_1 \succ_i a_s$ for all $i \leq n$ (otherwise intermediateness fails). Let us remove now vertex $n+1$ from the graph and linear order P_{n+1} from the profile. Then we get graph S_n and the profile $P' = (P_1, \dots, P_n)$ which is intermediate on S_n . No edge in S_n is an $a_1 a_s$ -cut now. Let us now remove the alternative a_1 from P' to obtain a profile $P'' = (P''_1, \dots, P''_n)$. Then P'' is still intermediate on the star S_n and we claim that P'' is reduced. If not, then after removal of a_1 , at least two linear orders, say P''_i and P''_k become equal. If $i = 1$, then the only cut the edge $1k$ had was an $a_1 a_t$ -cut for some $t > s$. Then we had $a_t \succ_k a_1 \succ_k a_s$ while $a_s \succ_1 a_t$; so we see that $1k$ had also a $a_s a_t$ -cut. This contradicts $P''_1 = P''_k$.

Now suppose $P''_i = P''_k$ with $i \neq 1$ and $k \neq 1$. Then P_i and P_k must agree on a_2, \dots, a_n . Due to intermediateness they must also agree with P_1 on these, i.e., $a_2 \succ_i \dots \succ_i a_n$ and $a_2 \succ_k \dots \succ_k a_n$. Since a_1 cannot be on the top of each of them (otherwise one would be equal to P_1) we have $a_2 \succ_i a_1$ and $a_2 \succ_k a_1$, which contradicts intermediateness.

Hence P'' is reduced. Since P'' has $n-1$ alternatives, this is a contradiction. \square

4 Algorithmic aspects of single-crossedness

4.1 A recognition algorithm.

The goal of this section is to give a polynomial-time algorithm for recognising intermediate profiles on median graphs. We need to know more about the structure of intermediate profiles on median graphs.

Theorem 4.1. Let $R = (R_1, \dots, R_n) \in \mathcal{L}(A)^n$ be a profile whose linear orders are indexed by the vertices of graph $G = (V, E)$. Let $a, b \in A$ be a pair of alternatives such that $\emptyset \neq V_{ab} \neq V$. Let also $e_i = u_i v_i$, $i = 1, \dots, s$ be the edges that connect V_{ab} and V_{ba} with $u_i \in V_{ab}$ and $v_i \in V_{ba}$. Then G is a median graph and R is intermediate on G iff

- (i) u_1, \dots, u_s are all distinct and so are v_1, \dots, v_s ;
- (ii) $S(e_1) = \dots = S(e_s)$;
- (iii) Induced graphs on V_{ab} and V_{ba} are median graphs in their own right;
- (iv) $R_{ab} = \{R_u \mid u \in V_{ab}\}$ and $R_{ba} = \{R_v \mid v \in V_{ba}\}$ are the profiles which are intermediate on V_{ab} and V_{ba} , respectively;
- (v) Let \bar{G} be the graph G with edges e_1, \dots, e_s contracted. Let \bar{V}_{ab} and \bar{V}_{ba} be images of V_{ab} and V_{ba} in \bar{G} . Then G is the convex expansion of \bar{G} with respect to \bar{V}_{ab} and \bar{V}_{ba} .

Proof. \implies (i) Suppose $v_i = v_j$, then $u_i \neq u_j$ and $(a, b) \in S(e_i) = S(e_j)$. Since G is bipartite it has no triangles, hence $u_i v_i u_j$ is the shortest path between u_i and u_j . This contradicts to intermediateness since R_{u_i} and R_{u_j} agree on (a, b) but R_{v_i} disagrees with them.

(ii) is Corollary 3.6.

(iii) Follows from an observation that a shortest path between vertices $w, w' \in V_{ab}$ cannot involve any of e_1, \dots, e_s and hence lies entirely in V_{ab} .

(iv) and (v) are now obvious.

\Leftarrow Firstly, G is median due to Mulder's theorem. To check intermediateness, let us consider a shortest path between u and v from V . If they are both in V_{ab} or V_{ba} , this case is clear. Suppose $u \in V_{ab}$ and $v \in V_{ba}$ and they agree on (c, d) for some $c, d \in A$. The shortest path between u and v contains one of the edges e_1, \dots, e_s , say e_i so it goes through vertices u, u_i, v_i, v . Since elements of V_{cd} are found both in V_{ab} and V_{ba} by Lemma 3.5 we cannot have $(c, d) \in S$, where $S = S(e_1) = \dots = S(e_s)$. Thus both $c \succ_{u_i} d$ and $c \succ_{v_i} d$. The part of the path connecting u and u_i is the shortest path in V_{ab} so all linear orders on this path agree with u and u_i on (c, d) . So do the linear orders on the path from v_i to v . This proves the theorem. \square

The idea of the recognition algorithm is now clear. We give the construction only for a reduced profile $R = (R_1, \dots, R_n)$. The order of linear orders in the profile can be ignored so we actually deal with the domain $\mathcal{D} = \{R_1, \dots, R_n\}$. Firstly, we identify the graph $G_{\mathcal{D}}$ to be tested. For this we find all pairs of 'neighboring' linear orders. Any two linear orders $P, Q \in \mathcal{D}$ define the 'interval' $[P, Q]$ as the set of all linear orders in \mathcal{D} which are between P and Q and call P and Q neighbors if $[P, Q] = \{P, Q\}$. We draw edges between the neighboring orders and obtain the graph $G_{\mathcal{D}}$ on linear orders from \mathcal{D} . The construction of this graph requires $O(m^2 n^3)$ operations, where m is the number of alternatives.

If R was intermediate on a median graph G , then $G_{\mathcal{D}}$ is exactly G . Indeed, if u and v were neighbors in G , then $[R_u, R_v] = \{R_u, R_v\}$. If only $R_w \in [R_u, R_v]$ for $w \neq u$ and $w \neq v$, then, since u and v are neighbors, the median $m(u, v, w)$ is either u or v . Suppose $m(u, v, w) = u$. Then,

due to intermediateness, R_u is between R_w and R_v from which $R_w = R_u$. On the other hand, if u and v are not neighbors in G , then it is easy to see that $[R_u, R_v] \neq \{R_u, R_v\}$.

We then pick any pair $(a, b) \in A$ for which V_{ab} and V_{ba} are both nonempty and select edges $e_i = u_i v_i$, $i = 1, \dots, s$ of $G_{\mathcal{D}}$. If all u_i 's and all v_i 's are different, and $S(e_1) = \dots = S(e_s)$, then the question of whether or not R is intermediate on $G_{\mathcal{D}}$ will be reduced to the questions of whether or not $R_{ab} = \{R_u \mid u \in V_{ab}\}$ and $R_{ba} = \{R_v \mid v \in V_{ba}\}$ are intermediate on graphs induced on V_{ab} and V_{ba} , respectively. This can be arranged as a recursive algorithm. We have proved

Theorem 4.2. For an input profile with n voters and m alternatives we can determine in time polynomial in m, n whether or not the given profile is intermediate on some median graph, and, if so, construct this graph.

4.2 Chamberlin-Courant rule

This section deals with single-crossing profiles on trees.

Given a society of n voters V with preferences over a set of m candidates A and a fixed positive integer $k \leq m$, a method of fully proportional representation outputs a k -member committee (e.g., parliament), which is a subset of A , and assigns to each voter a candidate that will represent this voter in the committee. The fully proportional representation rules, suggested by Chamberlin and Courant [1983] and Monroe [1995], have been widely discussed in Political Science and Social Choice literature alike [Potthof and Brams, 1998; Meir *et al.*, 2008; Betzler *et al.*, 2013].

It is well-known that on an unrestricted domain of preferences both rules are intractable in the classical [Meir *et al.*, 2008; Lu and Boutilier, 2011] and parameterized complexity [Betzler *et al.*, 2013] senses. [Skowron *et al.*, 2013], however, showed that for the classical single-crossing elections the winner-determination problem for the Chamberlin-Courant rule is polynomial-time solvable for every dissatisfaction function for both the utilitarian [Chamberlin and Courant, 1983] and egalitarian [Betzler *et al.*, 2013] versions of the rule. They also generalized this result to elections with bounded single-crossing width proving fixed-parameter tractability of the Chamberlin-Courant rule with single-crossing width as parameter. The concept of single-peaked width was defined in [Cornaz *et al.*, 2012].

Here we will prove that polynomial solvability remains for single-crossing profiles on any tree. But, firstly, we will remind the reader the definitions needed for discussing the Chamberlin-Courant rule. By $\text{pos}_v(c)$ we denote the position of the alternative c in the ranking of voter v ; the top-ranked alternative has position 1, the second best has position 2, etc.

Definition 4.3. Given a profile P over set A of alternatives, a mapping $r: P \times A \rightarrow \mathbb{Q}_0^+$ is called a misrepresentation function if for any voter $v \in V$ and candidates $c, c' \in A$ the condition $\text{pos}_v(c) < \text{pos}_v(c')$ implies $r(v, c) \leq r(v, c')$.

In the classical framework the misrepresentation of a candidate for a voter is a function of the position of the candidate in the preference order of that voter given by $s = (s_1, \dots, s_m)$, where $0 = s_1 \leq s_2 \leq \dots \leq s_m$, that is, the misrepresentation function in this case will be $r(v, c) =$

$s_{\text{pos}_v(c)}$. Such a misrepresentation function is called *positional*. An important case is the *Borda misrepresentation function* defined by the vector $(0, 1, \dots, m-1)$ which was used in [Chamberlin and Courant, 1983]. We assume that the misrepresentation function is defined for any number of alternatives and that it is polynomial-time computable.

In the approval voting framework, if a voter is represented by a candidate whom she approves, her misrepresentation is zero, otherwise it is equal to one. This function is called the *approval misrepresentation function*. It does not have to be positional since different voters may approve different numbers of candidates. In the general framework the misrepresentation function may be arbitrary.

By $w: V \rightarrow A$ we denote the function that assigns voters to representatives, i.e., under this assignment voter v is represented by candidate $w(v)$. If $|w(V)| \leq k$ we call it a *k-assignment*. The total misrepresentation $\Phi(P, w)$ of the given election under w is then given by $\Phi(P, w) = \ell(r(v, w(v)))$, where ℓ is used to mean either the sum or the maximum of a given list of values depending on the utilitarian or egalitarian model, respectively.

The Chamberlin-Courant rule takes the profile and the number of representatives to be elected k as input and outputs an optimal k -assignment w_{opt} of voters to representatives that minimizes the total misrepresentation $\Phi(P, w)$.

Theorem 4.4. *For any polynomial-time computable dissatisfaction function, every positive integer k , and for both utilitarian and egalitarian versions of the Chamberlin-Courant rule, there is a polynomial-time algorithm that given a profile $P = (P_1, \dots, P_n)$ over a set of alternatives $A = \{a_1, \dots, a_m\}$, which is single-crossing with respect to some tree, finds an optimal k -assignment function w_{opt} for P .*

Lemma 4.5. *Let $P = (P_1, \dots, P_n)$ be a reduced profile over a set $A = \{a_1, \dots, a_m\}$ of alternatives, where P is single-crossing with respect to a tree T . Let w_{opt} be an optimal k -assignment for P . Let voter 1 be an arbitrary vertex of T , and let $b \in A$ be the least preferred alternative of voter 1 in $w_{\text{opt}}(V)$. Then the vertices of $w_{\text{opt}}^{-1}(b)$ are vertices of a terminal subtree (a subtree whose vertex-complement is also a subtree) of T .*

Proof. On a tree T we may define the distance between any two vertices u and v which is the number of edges on the unique path connecting these two vertices. Let v be the closest vertex to 1 such that $w_{\text{opt}}(v) = b$. Let u be the vertex on that path which is one edge closer to 1 (it can be actually 1 itself). Due to minimality of T the edge (u, v) is an (a, b) -cut for some $a = w_{\text{opt}}(u)$ where $a \succ_1 b$. Let us show that $w_{\text{opt}}^{-1}(b) = V_{ba}$. Suppose first that $w_{\text{opt}}(v') = b$. Then $b \succ_{v'} a$ (otherwise v' would be assigned a) and hence $v' \in V_{ba}$. Suppose now $v' \in V_{ba}$. Then v' is connected by a path within V_{ba} , hence the unique path between 1 and v' passes through v . Since linear orders on this path form a classical single crossing subprofile we have $w_{\text{opt}}(v') = b$. \square

The fact that the least preferred alternative of voter 1 in the elected committee $w(V)$ represents voters in a terminal subtree of T is important in our design of a dynamic programming algorithm. We will fix an arbitrary leaf, without loss of

generality it will be voter 1, and reduce the problem of calculating an optimal assignment for a profile $P = (P_1, \dots, P_n)$ over a set of alternatives $A = \{a_1, \dots, a_m\}$ to a partially ordered set of subproblems which will be defined shortly. Let us denote the original problem as (P, A, k) . We define the set of subproblems as follows. A triple (P', A', k') , where $k' \leq k$ is a positive integer, P' is a subprofile of P and A' is a subset of A is a subproblem of (P, A, k) if

1. $P' = P_{ab}$, the subprofile of linear orders corresponding to the subset of vertices $V_{ab} \subseteq V$, where $a \succ_1 b$;
2. $A' = \{a_1, \dots, a_j\}$ for some positive integer j such that $k \leq j \leq n$;
3. the goal is to find an optimal assignment $w': V_{ab} \rightarrow A'$ with $|w'(V_{ab})| \leq k'$.

The idea behind this definition is based on Lemma 4.5. Namely, we can try to guess the least preferred alternative of voter 1 in the elected committee a_j and the terminal subtree V_{ba} whose voters are all assigned to a_j , then the problem will be reduced to choosing a committee of size $k-1$ among $\{a_1, \dots, a_{j-1}\}$ given the profile P_{ab} of voters corresponding to V_{ab} . We note that there are at most $n-1$ subproblems. Note that our cuts can be naturally ordered: we can say that ab -cut \subset cd -cut if and only if $V_{ab} \subset V_{cd}$.

Proof of Theorem 4.4. The tree T with respect to which P is single-crossing can be computed in polynomial time, by Theorem 4.2. We can identify one of the leaves then. Let this be voter 1 with preferences $a_1 \succ_1 \dots \succ_1 a_m$.

For every ab -cut, $j \in \{1, \dots, m\}$ and $t \in \{1, \dots, k\}$ we define $A[V_{ab}, j, t]$ to be the optimal dissatisfaction (calculated in the utilitarian or egalitarian way) that can be achieved with a t -assignment function when considering a subprofile $P' = \{P_{ab} \mid 1 \in V_{ab}\}$ over $A' = \{a_1, \dots, a_j\}$. It is clear that for $V \subseteq V, j \in M \setminus \{1\}$ and $t \in K \setminus \{1\}$, the following recursive relation holds

$$A[V, j, t] = \min \left\{ A[V, j-1, t], \min_{ab\text{-cut}} \ell(A[V_{ab}, j-1, t-1], (r(v_i, a_j))_{v_i \in V_{ba}}) \right\}.$$

Here ℓ is used to mean either the sum or the maximum of a given list of values depending on the utilitarian or egalitarian model, respectively. To account for the possibility that a_j is not elected in the optimal solution, we also include the term $A[V, j-1, t]$. Thus, $A[V, m, k]$ is then the optimal dissatisfaction, and in calculating it we simultaneously find the optimal k -assignment function.

The following base cases are sufficient for the recursion to be well-defined

- $A[\emptyset, j, t] = 0$;
- $A[V, j, 1] = \min_{j' \leq j} \ell((r(v_i, a_{j'}))_{i \in V})$;
- $A[V, j, t] = 0$ for $t \geq j$.

These conditions suffice for our recursion to be well-defined. Using dynamic programming, we can compute in polynomial time, in fact, in time $O(mn^2k)$, the optimal dissatisfaction of the voters and the assignment that achieves it. Note that the complexity is the same as for the classical case in [Skowron *et al.*, 2013] which we closely followed.

5 Conclusion

This paper generalises the classical single-crossing property to an intermediate property on median graphs and, in particular, to trees. We complement Demange’s representative voter theorem with the fact that the set of linear orders of any intermediate profile on a median graph is a Condorcet domain.

We prove that, for any median graph, there exists a profile of preferences which is intermediate with respect to that particular graph. Finally we present two results on algorithmic aspects of single-crossedness. The first one states that recognising intermediateness on median graphs is possible in polynomial time, and the second shows that the winner determination problem for the Chamberlin-Courant rule is also polynomial for single-crossing profiles on trees. We do not know whether or not this latest result can be extended to intermediate profiles on median graphs.

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