Low Resolution Information Also Matters: Learning Multi-Resolution Representations for Person Re-Identification

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Abstract

As a prevailing task in video surveillance and forensics field, person re-identification (re-ID) aims to match person images captured from nonoverlapped cameras. In unconstrained scenarios, person images often suffer from the resolution mismatch problem, i.e., Cross-Resolution Person Re-ID. To overcome this problem, most existing methods restore low resolution (LR) images to high resolution (HR) by super-resolution (SR). However, they only focus on the HR feature extraction and ignore the valid information from original LR images. In this work, we explore the influence of resolutions on feature extraction and develop a novel method for cross-resolution person re-ID called Multi-Resolution Representations Joint Learning (MRJL). Our method consists of a Resolution Reconstruction Network (RRN) and a Dual Feature Fusion Network (DFFN). The RRN uses an input image to construct a HR version and a LR version with an encoder and two decoders, while the DFFN adopts a dual-branch structure to generate person representations from multi-resolution images. Comprehensive experiments on five benchmarks verify the superiority of the proposed MRJL over the relevent state-of-the-art methods.

1 Introduction

Person re-identification (re-ID) is a retrieval task of recognizing the same person across images from non-overlapped cameras, which has attracted increasing attention in computer vision community due to its wide application prospects in video surveillance and forensics field [Zheng *et al.*, 2016]. Nevertheless, person re-ID remains a challenge due to some complicated visual variations in real scenarios such as viewpoint, illumination, person pose and background clutter.

Most existing re-ID methods focus on the designment of feature extraction networks or matching distance metrics on the basis of the assumption that all captured images share similar and sufficiently high resolutions. However, this assumption only exists in an absolutely ideal condition. In real

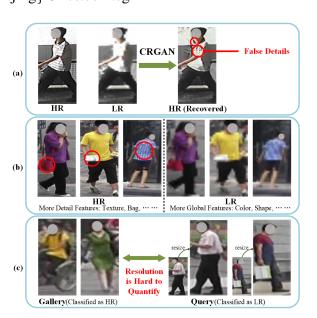


Figure 1: Several shortages and limitations of existing crossresolution person re-ID methods. (a) The recovered HR image with CRGAN may contain a few false details which may mislead the feature extraction. (b) HR images contain plenty of detail information, such as texture and bags, while current methods have not yet exploited complementary global features of LR images. (c) In some cases, resolution is hard to quantify with image pixel size. Some gallery images classified as HR even have worse visual quality than query images classified as LR.

and unconstrained scenarios, affected by some objective factors such as shooting distance and camera pixels, the captured images have variable resolutions. The problem of matching person images with variable resolutions is defined as *Cross-Resolution Person Re-ID*.

Recently, a few researchers have paid attention to this problem and proposed some high-performance methods which can be mainly divided into two categories: 1) traditional methods utilizing metric learning or dictionary learning [Jing et al., 2015; Li et al., 2015] and 2) deep learning methods applying super-resolution (SR) technology to restore LR images to HR images, which are most commonly used in cross-resolution person re-ID [Jiao et al., 2018; Mao et al., 2019;

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Wang et al., 2018b]. However, there are still problems in existing SR based methods, just as illustrated in Figure 1. 1) Existing methods mainly focus on recovering higher resolution images and extract HR feature representations. Although the complementary details generated by SR give person images better visual quality, these details may not be real in person appearances. Therefore, in some cases, the features extracted from these generated HR images are not discriminative enough to match correct persons. 2) Although local details are lost in LR images, LR images still can provide some global information, such as body shape and color, as evidenced in the studies of pyramid representation of images [Yoo et al., 2015]. These LR features can complement HR features which may be false details, but all existing methods neglect this useful information. 3) Most existing methods process gallery and query images with different strategies separately, because they tacitly approve all gallery images as HR and all query images as LR. However, in some practical scenarios, the resolutions of gallery or query images are not clearly divided, making it difficult to quantify the image as HR or LR.

In this paper, we investigate the influence of resolution on feature extraction and find that a neural network focuses on more local details in HR person images but more global features in LR person images. Inspired by this, we propose a novel Multi-Resolution Representations Joint Learning (MRJL) for cross-resolution person re-ID, which fully utilizes the detail information in HR and complementary information in LR. Our MRJL is made up of two sub-networks named as Resolution Reconstruction Network (RRN) and Dual Feature Fusion Network (DFFN). The RRN adopts a multi-kernel encoder to encode the input image into a feature map, and then applies two different decoders to restore the feature map to HR image and LR image, respectively. The DFFN utilizes a dual-branch structure based on the PCB method [Sun et al., 2018] to generate person representations from multi-resolution images. It is worth noting that in the testing phase, our MRJL does not need to know the resolution of input image and treats images with different resolutions equally.

The contributions of our work are summarized as follows:

1) As far as we know, it is the first work to detailly explore the influence of resolution on feature extraction in person reidentification. 2) A novel method named as Multi-Resolution Representations Joint Learning (MRJL) is proposed for cross-resolution person re-ID, which fully utilizes features contained in different resolutions.

2 Related Work

2.1 Person Re-ID

In the past decade, a variety of high-performance methods have sprung up in the field of person re-ID. Most of these existing methods attempt to extract more discriminative features and overcome the difficulties such as pose changes and background clutter. For instance, some methods [Sun *et al.*, 2018; Wang *et al.*, 2018a] divide person image into several parts and extract local features which contain more discriminative details. Nevertheless, pose changes will affect the feature align-

ment. To address this problem, some excellent methods adopt pose-transferable GAN [Liu et al., 2018] or pose estimation [Zhao et al., 2017] to enhance the robustness of network towards pose variations. To attenuate background clutter, some methods apply semantic parsing [Kalayeh et al., 2018] to remove backgrounds or apply attention mechanism [Li et al., 2018] to train the network to focus on more informative areas. However, all above methods are limited in practical use due to the incapability of adaptation to variable image resolutions in unconstrained scenarios.

2.2 Cross-Resolution Person Re-ID

To meet the challenge of cross-resolution person re-ID, a series of methods have been proposed and can be divided into two categories: 1) methods based on metric learning or dictionary learning and 2) methods based on SR. In the first category, Jing *et al.* [Jing *et al.*, 2015] develop a semi-coupled low-rank dictionary learning approach to learn the mapping between HR and LR images. Li *et al.* [Li *et al.*, 2015] introduces a learning framework which jointly performs cross-scale image domain alignment and distance metric learning. However, the matching capability of these methods is limited due to the lack of fine-grained details in LR images.

The success of super-resolution (SR) technology promotes the development of cross-resolution person re-ID. The key idea of these methods is to restore LR images back to HR images by resolution reconstruction loss or GAN. Both [Jiao et al., 2018] and [Mao et al., 2019] design a jointly learning framework which simultaneously optimize a SR model and a re-ID model. Wang et al. [Wang et al., 2018b] present a cascaded structure to enhance image resolution step by step with the repeated use of SR-GAN [Ledig et al., 2017]. Li et al. propose successively RAIN [Chen et al., 2019] and CAD-Net [Li et al., 2019]. The former adopts GAN to generate resolution-invariant representations, while the latter adds the features extracted from recovered images and achieves better performance. Cheng et al., [Cheng et al., 2020] introduce a training regularization method which utilizes the underlying association knowledge between SR and re-ID as an extra learning constraint to enhance the compatibility between two networks. Han et al. [Han et al., 2020] propose an end-to-end PRI framework to adaptively predict the preferable scale factor, recover details for LR images and perform the identification. However, all above methods only focus on the HR features and neglect the useful information in LR images. In this work, we explore the influence of resolutions on feature extraction and verify that LR information matters for cross-resolution person re-ID. Based on the above idea, we develop a novel method fully utilizing features of different resolutions.

3 Proposed Method

3.1 Framework Overview

As illustrated in Figure 2, our proposed MRJL contains two sub-networks, RRN and DFFN. In the training phase, we define a set of input HR images with associated labels as $D_H = \{x^H, y\}$, where $x^H \in \mathbb{R}^{H \times W \times 3}$ represents a HR image and $y \in \mathbb{R}$ represents its identity label. To train

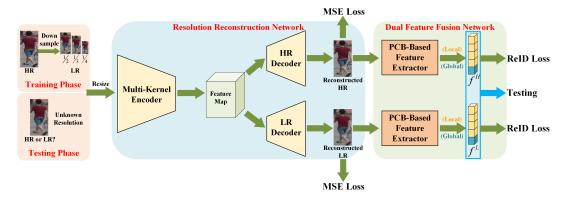


Figure 2: The architecture of the proposed MRJL. This framework consists of two jointly trained sub-networks, Resolution Reconstruction Network (RRN) and Dual Feature Fusion Network (DFFN). The former is tasked to reconstruct input images into two versions with different resolutions, while the latter is used to extract feature representations from the generated HR and LR images.

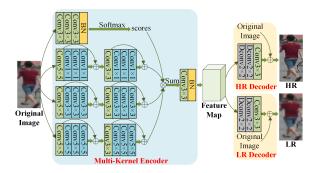


Figure 3: The details of the Resolution Reconstruction Network.

the RRN with the capability to reconstruct different resolutions of images, we down-sample each HR image with the down-sampling rate $r \in \{2,3,4\}$ (i.e., the spatial size of the down-sampled image becomes $\frac{H}{r} \times \frac{W}{r}$) and resize them back to the original size. The set of generated LR images obviously share the same identity labels and are denoted as $D_L = \left\{\left(x_2^L, x_3^L, x_4^L\right), y\right\}$ where $x_i^L \in \mathbb{R}^{H \times W \times 3}$ is a LR image and the subscript $i \in \{2,3,4\}$ represents the down-sampling rate. (The subscript i is omitted in following paper for simplicity unless necessary.) In the testing phase, our framework regards the resolution of inputs as unknown, and processes the gallery (HR) and query (LR) equally.

In order to generate both HR and LR images for an input image with unknown resolution, we design the RRN module which is made up of an encoder and two independent decoders. The encoder is utilized to extract feature map from an input image, and the two decoders reconstruct the feature map into HR version and LR version, respectively. The DFFN module adopts a dual-branch structure to extract the feature representations $f^H \in \mathbb{R}^d$ and $f^L \in \mathbb{R}^d$ (d denotes the dimension of feature) from the generated HR and LR images, respectively. Note that the two branches don't share parameter weights. As for testing, feature representations f^H and f^L of all images in gallery and query sets are computed, and then the concatenation $f = \left[f^H, f^L \right] \in \mathbb{R}^{2d}$ will be used for distance measure.

3.2 Resolution Reconstruction Network (RRN)

Before feature extraction, the quality of generated images greatly affects the discrimination of representations. The proposed RRN module consists of a multi-kernel encoder, a HR decoder and a LR decoder, as shown in Figure 3.

The multi-kernel encoder (ME) has a four-branch structure that consists of three feature perception branches and an attention branch. All the perception branches are made up of 8 convolutional layers, and the attention branch has 3 convolutional layers followed by a batch normalization layer and a softmax activation function. To make the network perceive features of different scales, the kernel sizes of these perception branches are different, which are set to $\{1, 3, 5\}$, respectively. Motivated by the previous works in SR [Mao et al., 2019; Mao et al., 2016], several skip connections are introduced to RRN to preserve the original visual cues and help reconstruct HR images. Besides, attention mechanism [Vaswani et al., 2017] has widely applied in neural network to make the network focus on parts of interest. In RRN, the attention branch is used to train the encoder to focus on the interested perceptual scale and then learn three attention weights for corresponding perception branches. The output feature map of the encoder is a weighted sum of all the outputs from the individual branch.

The HR decoder (HD) and LR decoder (LD) adopt the same network structure but don't share parameter weights. Both decoders have 2 deconvolution layers and 1 convolution layers. For each input image x (It doesn't matter whether it is x^H or x^L), our RRN can reconstruct both HR and LR images as:

$$\tilde{x}^{H} = HD\left(ME\left(x\right)\right), \tilde{x}^{L} = LD\left(ME\left(x\right)\right) \tag{1}$$

According to the formula above, if the training input is a HR image x^H , its reconstructed HR version and reconstructed LR version are denoted as \tilde{x}^{H2H} and \tilde{x}^{H2L} , respectively. Similarly, if the training input is a LR image x^L , its two reconstructed versions are denoted as \tilde{x}_i^{L2H} and \tilde{x}_i^{L2L} , where the subscript $i \in \{2,3,4\}$ represents the corresponding down-sampling rate.

As illustrated in Figure 4, pixel-wise Mean Square Error (MSE) loss [Dong et al., 2015] is applied in the training

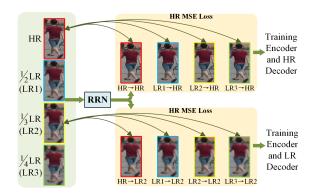


Figure 4: The training strategy of RRN, consists of two aspects: 1) training the reconstructed HR images to be visually closer to the original HR images, and 2) training the reconstructed LR images to be visually closer to the standard LR images.

strategy of RRN which simultaneously trains the encoder and two different decoders. Since these LR images have variable resolutions with different down-sampling rates picked from $\{2,3,4\},$ we should set a LR reference standard for RRN. Here we select the median x_3^L in LR images as the standard. To train the encoder and decoders, the HR MSE loss L_{mse}^H and the LR MSE loss L_{mse}^L are calculated as:

$$L_{mse}^{H} = \left\| \tilde{x}^{H2H} - x^{H} \right\|_{2}^{2} + \sum_{i=2}^{4} \left\| \tilde{x}_{i}^{L2H} - x^{H} \right\|_{2}^{2}$$
 (2)

$$L_{mse}^{L} = \|\tilde{x}^{H2L} - x_3^L\|_2^2 + \sum_{i=2}^{4} \|\tilde{x}_i^{L2L} - x_3^L\|_2^2$$
 (3)

Then we get the joint MSE loss in RRN as:

$$L_{mse} = L_{mse}^{LR} + \lambda L_{mse}^{HR} \tag{4}$$

where λ is a hyper-parameter to control the importance of HR MSE loss.

3.3 Dual Feature Fusion Network (DFFN)

A dual-branch structure is used in DFFN to extract both detailed information from HR images and complementary information in LR images simultaneously. Two branches in DFFN share the same network but do not share parameter weights since we wish each branch to focus on different types of features from images with different resolution. Here we adopt the feature extractor on the basis of PCB method [Sun et al., 2018]. The 3D tensor generated by the backbone network (e.g., ResNet50) is segmented into 4 horizontal stripes. Followed by an average pooling layer and 1×1 convolutional layers, the feature representation $f^H = \begin{bmatrix} f_1^H, f_2^H, f_3^H, f_4^H, f_5^H \end{bmatrix}$ (or $f^L = \begin{bmatrix} f_1^L, f_2^L, f_3^L, f_4^L, f_5^L \end{bmatrix}$) is obtained which is concatenated by 4 256-dimentional local features and a 512-dimentional global feature.

In DFFN, we adopt both triplet loss and cross entropy loss to enhance the discrimination of feature representations:

$$L_{reid} = L_{ce} + \gamma L_{trip} \tag{5}$$

where γ is a hyper-parameter to control the importance of triplet loss. The cross entropy loss L_{ce} can be computed as:

$$L_{ce} = -\sum_{i=1}^{5} \left(y \log \left(FC\left(f_{i}^{H} \right) \right) + y \log \left(FC\left(f_{i}^{L} \right) \right) \right)$$
 (6)

where y denotes the ground truth and the predicted person label can be generated by FC layers. The triplet loss L_{trip} can be calculated as:

$$L_{trip} = \sum_{i=1}^{5} \sum_{f_{a,i}^{H}, f_{p,i}^{H}, f_{n,i}^{H}} \left[d\left(f_{a,i}^{H}, f_{p,i}^{H}\right) - d\left(f_{a,i}^{H}, f_{n,i}^{H}\right) + m \right]_{+} + \sum_{i=1}^{5} \sum_{f_{a,i}^{L}, f_{p,i}^{L}, f_{n,i}^{L}} \left[d\left(f_{a,i}^{L}, f_{p,i}^{L}\right) - d\left(f_{a,i}^{L}, f_{n,i}^{L}\right) + m \right]_{+}$$

$$(7)$$

where $f_{a,i}^H$, $f_{p,i}^H$ and $f_{n,i}^H$ indicate the i^{th} sub-features extracted from anchor, positive and negative HR samples ($f_{a,i}^L$, $f_{p,i}^L$ and $f_{n,i}^L$ indicate the corresponding features from LR samples), $d(\cdot, \cdot)$ indicates the Euclidean distance, and m is a margin hyper-parameter to control the differences between intra and inter distances.

4 Experiment

4.1 Datasets

Five person re-ID datasets are used to evaluate our proposed method, including four synthetic Multiple Low Resolutions (MLR) datasets and one real-world dataset. The generation strategy of MLR datasets refers [Jiao et al., 2018; Li et al., 2019; Cheng et al., 2020]. Specifically, we downsample images from one camera by randomly selecting a down-sampling rate $r \in \{2,3,4\}$, while the images captured by other camera(s) remain unchanged. 1) MLR-SYSU is constructed from the SYSU [Chen et al., 2016]. SYSU contains 502 identities captured by 2 cameras, and three images per person are randomly selected for each camera. Half of these identities are for training and half are for testing. 2) MLR-VIPeR is a synthetic version built from the VIPeR [Gray and Tao, 2008]. VIPeR contains 632 person image pairs taken by 2 cameras. According to the identity labels, these pairs are divided into 2 non-overlapping halves. 3) MLR-CUHK03 is based on the CUHK03 [Li et al., 2014]. CUHK03 is composed of five different pairs of camera views, and has 14,097 images of 1,467 identities. We use the 1367/100 training/testing identity split. 4) MLR-**Market-1501** is built from the Market-1501 [Zheng et al., 2015]. Market-1501 comprises more than 32,000 images of 1,501 identities from 6 cameras, and we utilize 751/750 training/testing identity split. 5) CAVIAR [Cheng et al., 2011] is a challenging real-world person re-ID dataset which contains 1220 images of 72 identities captured by 2 cameras. Among them, 22 persons who appear only in the close camera are discarded. Similar to MLR-VIPeR, we split the remaining images into 2 non-overlapping halves.

4.2 Implementation Details

In the training phase, all the input images are resized to 128×256 . A mini-batch has 20 images of 5 persons where

Method	Publication	MLR-SYSU		MLR-VIPER		MLR-CUHK03		MLR-Market-1501		CAVIAR	
	1 ublication	Rank-1	Rank-5	Rank-1	Rank-5	Rank-1	Rank-5	Rank-1	Rank-5	Rank-1	Rank-5
JUDEA [Li et al., 2015]	ICCV'15	18.3	41.9	26.0	55.1	26.2	58.0	-	-	22.0	60.1
SLD ² L [Jing <i>et al.</i> , 2015]	CVPR'15	20.3	34.8	20.3	44.0	-	-	-	-	18.4	44.8
SDF [Wang et al., 2016]	IJCAI'16	13.3	26.7	9.3	38.1	22.2	48.0	-	-	14.3	37.5
SING [Jiao et al., 2018]	AAAI'18	50.7	75.4	33.5	57.0	67.7	90.7	74.4	87.8	33.5	72.7
CSR-GAN [Wang et al., 2018b]	IJCAI'18	-	-	37.2	62.3	70.7	92.1	76.4	88.5	32.3	70.9
FFSR+RIFE [Mao et al., 2019]	IJCAI'19	-	-	41.6	64.9	73.3	92.6	-	-	36.4	72.0
RAIN [Chen et al., 2019]	AAAI'19	-	-	42.5	68.3	78.9	97.3	-	-	42.0	77.3
CDA-Net [Li et al., 2019]	ICCV'19	-	-	43.1	68.2	82.1	97.4	83.7	92.7	42.8	76.2
PCB+PRI [Han et al., 2020]	ECCV'20	-	-	-	-	86.2	97.9	88.1	94.2	44.3	83.7
INTACT [Cheng et al., 2020]	CVPR'20	-	-	46.2	73.1	86.4	97.4	88.1	95.0	44.0	81.8
MRJL (Ours)		73.0	87.3	58.7	84.1	90.7	95.7	90.1	95.6	61.2	82.4

Table 1: Comparisons of our proposed method to the state-of-the-arts (%). Red and blue bold numbers indicate the 1st and 2nd top results.

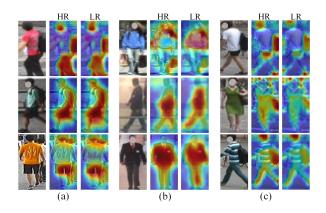


Figure 5: Examples of feature response maps extracted on different resolution samples. All the cases are classified into three groups.

2 HR images (each HR image can generate 3 down-sampled LR versions) and 2 original LR images are selected for each person. Noting that original LR samples are only utilized to train the DFFN module. Hyper-parameters λ , γ and m are set to 100, 1, 0.5, respectively. We select Adam to optimize our model with weight decay 5×10^{-4} . For parameters in the MSE loss, we set a learning rate of 3×10^{-3} , and for parameters in the re-ID loss, we set a learning rate of 3×10^{-4} . Our model is trained for 60 epochs in total, and the learning rates are decreased by 0.1 after 30 epochs.

4.3 Comparison with State-of-the-art Approaches

We compare our method with several recent cross-resolution person re-ID methods, and the comparable results are reported in Table 1, which show that the SR based methods commonly achieve better performance than the traditional methods. One important reason is that these SR based methods aid in the recovery of missing spatial information that contains more discriminative features. In contrast, traditional methods are incapable of recovering the lost information, resulting in poor performance. From Table 1, we can also observe that our proposed MRJL outperforms the state-of-thearts by 22.3%, 12.5%, 4.3%, 2.0% and 17.2% in Rank-1 on MLR-SYSU, MLR-VIPeR, MLR-CUHK03, MLR-Market-1501 and CAVIAR, respectively. The performance superiority of our method can be mainly attributed to the joint representations of both HR and LR features. All existing SR based

Resolution		CAVIAR			
Resolution	SYSU	VIPeR	CUHK03	Market-1501	(Rank-1)
(1.1) HR	68.0	54.0	90.7	88.9	50.1
(1.2) LR	70.0	48.9	88.8	88.4	53.6
(1.3) HR+LR	73.0	58.7	90.7	90.1	61.2

Table 2: Effects of different resolutions(%).

methods only extract features from recovered HR images but ignore the complementary information provided by LR ones.

4.4 Ablation Study

Influence of Resolutions on Feature Extraction

To investigate the influence of resolution on feature extraction, we conduct the following experiments as shown in Table 2. The variant (1.3) extracts the joint HR and LR feature representations, while the variant (1.1) and variant (1.2) only utilize the single branch in RRN and DFFN. The comparison results confirm two assumptions: 1) LR information also matters for cross-resolution person re-ID. LR features can provide complementary information for HR features and further improve the accuracy of matching. 2) Compared with HR images, networks can extract more discriminative features from LR images in some cases, such as on MLR-SYSU and CAVIAR datasets.

Figure 5 visualizes some feature response maps extracted from different resolution samples which further verify the above viewpoints. We classify the different cases into 3 groups. Most cases are similar to the group (a), which reflects that the network can extract similar features from HR and LR images. Group (b) shows that the network extract more global information from LR images compared with HR ones, and group (c) indicates that HR images make it easier for the network to focus on detail information, such as bags and textures. These experiments can provide a reasonable explanation for the pending phenomenon mentioned in [Mao et al., 2019] that re-ID model achieves lower accuracy when the recovered images become higher resolution. Although the recovered images obtain better visual quality, they have higher risk to generate false details which may mislead feature extraction. In most cases, LR images can still provide discriminative features for matching.

Analysis on RRN

To evaluate the validity of RRN module, we conduct the following ablation experiments. Firstly, we compare the single-



Figure 6: Visual results of the reconstructed HR and LR images. The group (a) and (b) represent the situations that the input is a LR (query) or HR (gallery) image, respectively.

Encoder Structure		CAVIAR			
Encoder Structure	SYSU	VIPeR	CUHK03	Market-1501	(Rank-1)
(2.1) Single-Branch	71.9	57.8	90.6	89.8	54.0
(2.2) Multi-Kernel	73.0	58.7	90.7	90.1	61.2

Table 3: Effects of different encoder structures in RRN (%).

branch encoder (variant (2.1)) and our multi-kernel encoder (variant (2.2)), and the comparable results are listed in Table 3. It can be observed that, compared with variant (2.1), variant (2.2) achieves higher accuracy on all datasets. The results prove the effectiveness of multi-kernel structure which can perceive features of different scales.

In addition, we test the different LR standards in the training strategy of RRN. During the training phase of RRN, HR images have the definite standard that the original images without down-sampling. Nevertheless, the LR images have variable down-sampling rates which mean different reference standards for reconstructing LR images, as shown in Figure 4. Table 4 reports that it is best to choose LR images with down-sampling rate 3 as the LR reference standard in most datasets except for MLR-CUHK03. The LR standard determines the resolution of reconstructed LR images. The results indicate that the discrimination of LR features will decrease if the reconstructed LR images are too close to HR images or too vague to mine features. Note that MLR-CUHK03 achieves the best performance when the LR standard is x_4^L . It means x_3^L cannot provide enough complementary information on MLR-CUHK03, which is also reflected on Table 2, and the better LR feature extraction needs lower resolution of reconstructed LR images. One possible explanation is that the samples in MLR-CUHK03 is relatively clearer, which limit the advantages of LR complementary effects.

To further verify the reconstruction capability of RRN, we visualize the reconstructed images. The two groups in Figure 6 reflect that RRN is capable of generating HR and LR images regardless the resolution of the input image.

Analysis on Unknown Resolution Strategy

We divide the cross-resolution person re-ID into two categories: unknown resolution and known resolution, as illustrated in Figure 7. In the case of known situation, we assume the gallery images are all HR and the query images are all LR, and SR networks only need to pre-process the LR images. In the other case, we treat all the images equally in both gallery and query sets since networks needn't know image

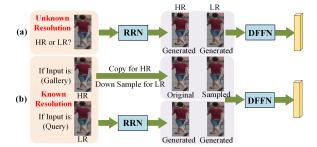


Figure 7: The method structures of (un)known resolution situations.

Standard -		CAVIAR			
	SYSU	VIPeR	CUHK03	Market-1501	(Rank-1)
$(3.1) x_2^L$	72.8	58.1	90.4	90.0	57.2
$(3.2) x_3^L$	73.0	58.7	90.7	90.1	61.2
$(3.3) x_4^L$	71.7	55.9	92.3	89.9	57.6

Table 4: Effects of different LR reference standards in RRN (%).

resolutions. Compared with known resolution case, unknown resolution case has two advantages: 1) Unknown resolution methods don't need the resolution labels which are hard to quantify with pixel size. 2) The unknown resolution case is closer to the unconstrained scenarios, because resolutions of images will not be divided neatly in some practical applications. Table 5 reports that our unknown resolution structure (variant (4.2)) achieves a few improvements, which can be explained that a few LR gallery images are mistaken for HR due to the classification by pixel size in structure (b).

Method		CAVIAR			
	SYSU	VIPeR	CUHK03	Market-1501	(Rank-1)
(4.1) Known	72.6	56.5	90.6	89.6	60.8
(4.2) Unknown	73.0	58.7	90.7	90.1	61.2

Table 5: Effects of different method structures(%).

5 Conclusion

In this paper, we have investigated into the influence of resolutions on feature extraction, and proposed a Multi-Resolution Representation Joint Learning (MRJL) method to solve the cross-resolution person re-ID problem. By a series of experiments, we explore the effectiveness of LR features which is capable of complementing HR features. According to the inspiration, the MRJL utilizes a Resolution Reconstruction Network (RRN) to generate both HR and LR versions no matter what the input resolution is. Besides, a Dual Feature Fusion Network (DFFN) is designed to extract discriminative multi-resolution representations. Extensive experimental results on five challenging datasets demonstrate the superiority of the MRJL over the relevant state-of-the-art methods.

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