## Spatio-Temporal Change Detection Using Granger Sequence Pattern

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#### **Abstract**

This paper proposed a method to detect changes in causal relations over a multi-dimensional sequence of events. Cluster Sequence Mining algorithm was modified to extract causal relations in the form of *g-patterns*: a pair of clusters of events that have their occurrence time determined by Granger causality. This paper also proposed the pattern time signature, a probabilistic density function of the cluster sequence occurring at any given time. Synthetic data were used for validation. The result shows that the proposed algorithm can correctly identify the changes in causal relations even under noisy data.

### 1 Introduction

Spatio-temporal data is very common in real world, for example, weather system and social network. This work aims to detect a causal relation change from an input of a multi-dimensional event sequence. Specifically, given a sequence of multi-dimensional events along with their time stamps, this paper aims to find the appearances and disappearances of causal relations in the input data. Spatio-temporal causal relations in the real world include relations between weather system, or relations between earthquake and aftershock, of which the changes in the relations might indicate something is happening. For example, in Fig. 1, at time  $t_0$ , there is a causal relation from cluster A to B, and from B to C. However, at time  $t_1$ , the relation B to C has gone, but there is now have new relation B to D. Then, at time  $t_2$ , all the existing relations have gone, with the new relation A to C occurring

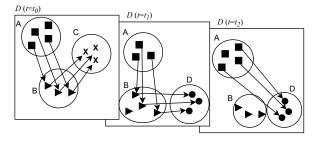


Figure 1: Example of changes in causal relation

instead. Current research in spatio-temporal change detection [Atluri *et al.*, 2018] does not try to detect any *changes in relations* at all.

One of the accepted methods to detect causality is a *Granger causality measure* [Granger, 1969]. Granger causality is based on the idea that: *if A causes B, then it must be easier to predict B using all available data than to predict B using all available data except A.* 

The Cluster Sequence Mining (CSM) algorithm [Fukui *et al.*, 2019] can be used to detect occurrence correlations in a multi-dimensional event sequence, but it does not detect causation. To the best of our knowledge, no existing methods can extract causal relations from spatio-temporal data.

This paper proposed a novel method of detecting changes in causal relations. Specifically, the CSM algorithm was extended with the adaption of the Granger causality for point process model [Kim *et al.*, 2011] to detect causal relation. This paper then introduced the *Pattern Time Signature* of each relation, which was a probabilistic distribution of each relation over time. The change points could be calculated using the aforementioned pattern time signature.

Changes in spatio-temporal relationships may further understanding of many natural phenomenons. Furthermore, as many scientific researches focused on detection a causal relation, the changes are also important.

# 2 Granger Cluster Sequence Mining (G-CSM)

Assuming an event sequence  $X = \{\mathbf{x}^{(i)} \in \mathbf{R}^n\}$  (|X| = N) with associated timestamps  $t(\mathbf{x}^{(i)})$  where  $t(\mathbf{x}^{(1)}) < t(\mathbf{x}^{(2)}) < ... < t(\mathbf{x}^{(N)})$ , Granger cluster sequence pattern pattern (g-pattern) is defined with prior event cluster  $\mathbf{A}$  and posterior event cluster  $\mathbf{B}$  as:

$$S_{A \to B} = \langle \mathbf{A} = \{ \mathbf{x}^{(i)} | A^i = 1 \}, \mathbf{B} = \{ \mathbf{x}^{(i)} | B^i = 1 \} \rangle,$$
 (1)

where A and B is an assignment vector for set  $\mathbf{A}$  and  $\mathbf{B}$  respectively.  $\langle t(\mathbf{x}^{(i)})|A^i=1\rangle$  must also Granger-cause  $\langle t(\mathbf{x}^{(i)})|B^i=1\rangle$ .

To extract *g-patterns* from the input event sequence, this paper substantially modified the CSM algorithm [Fukui *et al.*, 2019]. Specifically, the time proximity of the original CSM was replaced with Granger causality based measure. Pairwise

point-process Granger causality was adapted from [Kim *et al.*, 2011] to determine the Granger causality between the prior and posterior event cluster.

A log-cumulative incidence function (log-CIF)  $\lambda_b$  of event **B** is defined as follow:

$$\log \lambda_b(t|\theta_b, H_b(t)) = \theta_{b,0} + \sum_{q \in \{A,B\}} \sum_{m=1}^{M_b} \theta_{b,q,m} R_{q,m}(t),$$
(2)

where  $\theta_b$  is the parameter vector,  $M_b$  is the history length to consider, and  $R_{q,m}(t)$  is the counting measure for events occurring between time [t-mW,t-(m-1)W] with W specifying the windows length.

A log-likelihood point process was used fit the parametric CIF in eq. (2). The Granger causality strength is then given as:

$$\Gamma(S_{A\to B}) = \log \frac{L_b(\theta_b^a)}{L_b(\theta_b)},\tag{3}$$

where the likelihood  $L_b(\theta_b)$  was obtained from model fitting eq. (2), and the likelihood  $L_b(\theta_b^a)$  was obtained using new CIF with history of **A** cut. The Granger causality strength in eq. (3) was used to determined time proximity function  $\mathcal{F}$  as in eq. (4). The final evaluation score,  $\mathcal{L}$ , in eq. (5) is the same as in original CSM.  $\tau$  is an adjusting parameter.

$$\mathcal{F}(S_{A\to B}) = 1 + \frac{\tau}{\Gamma(S_{A\to B})},\tag{4}$$

$$\mathcal{L}(S_{A\to B}) = \mathcal{F}(S_{A\to B})^{\gamma} \cdot \mathcal{G}(\mathbf{A}, \mathbf{B})^{(1-\gamma)}.$$
 (5)

The candidates were ranked and eliminated in the same manner as in the original CSM.

### 3 Change Detection

A Pattern Time Signature for any g-pattern  $S_{A\to B}$  is a probabilistic density function  $P(S_{A\to B};t)$ , and is defined as:

$$P(S_{A\to B};t) = \int P(\mathbf{A};t)$$

$$P(\mathbf{B};t + t_{AB}|\mathbf{A};t)\Psi(t_{AB})dt_{AB}, \quad (6)$$

where  $P(\mathbf{A};t)$  is the probability density of event  $\mathbf{A}$  at time t,  $P(\mathbf{B};t+t_{AB}|\mathbf{A};t)$  is the probability density of event  $\mathbf{B}$  at time  $t+t_{AB}$  given that event  $\mathbf{A}$  occurred at time t, and  $\Psi(t_{AB})$  is the likelihood of  $t_{AB}$ .

To approximate  $P(\mathbf{A};t)$  and  $P(\mathbf{B};t+t_{AB}|\mathbf{A};t)$ , a kernel density method with Gaussian kernel was used. Bandwidth was chosen with the Silverman method. Each *g-pattern* was considered active (i.e. presence at a specific time) if the value of the time signature was above a set threshold.

## 4 Experiments

As with all causal detection, real-world data with known ground-truth are hard to come by. Synthetic data were used to test the proposed method. Relations were generated by sampling from two Gaussian distributions representing prior and posterior events, with time interval following an exponential distribution. Noise was randomly generated. The data distribution is shown in Fig. 2a, with different active time as shown

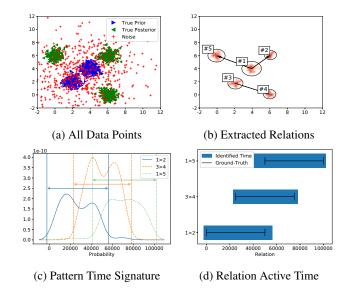


Figure 2: Experiment Result on Synthetic Data

in the black line in Fig. 2d. The algorithm correctly identified three relations as shown in Fig. 2b. The time signature and active time are shown in Fig. 2c and 2d respectively. The identified active time was very close to the ground truth.

### 5 Conclusion

This paper proposed an algorithm for change detection of causal relations using *pattern time signature* along with G-CSM algorithm. The experiment with synthetic data shows that the method could identify correct relations, even under noisy environment.

However, there are still limitations of the proposed methods. It cannot detect other kinds of changes, and the G-CSM algorithm is still susceptible to temporal noise. Experiments also need to be done on real-world data.

### References

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